

# Approximate aggregation methods and spatially distributed structured population discrete models

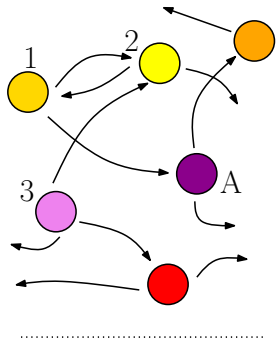
An application to a spatially competition model

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# General settings



Population divided in  $c$  classes

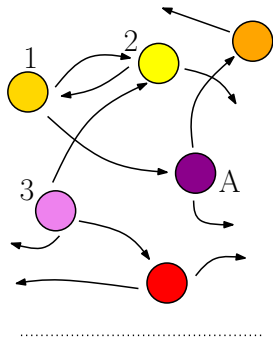
$$\vec{N} = (\vec{N}_1, \dots, \vec{N}_c)$$

Spatial distribution of individuals  
of class  $j$

$$\vec{N}_j = (N_{j1}, \dots, N_{jA})$$

$p_{rs}^j$  fraction of individuals of class  $j$   
patch  $s \rightarrow$  patch  $r$

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Matrix  $\mathcal{F}_j = (p_{rs}^j)$  is stochastic; movements are given by

$$\vec{N}(t+1) = \text{diag}(\mathcal{F}_1, \dots, \mathcal{F}_c) \vec{N}(t) = \mathcal{F} \vec{N}(t)$$

Local interactions are described by matrix  $\mathcal{S}(N)$

$$\vec{N}(t+1) = \mathcal{S}(\vec{N}(t)) \vec{N}(t)$$

# General settings

- Local interactions are slower than individual displacements.
- Two time scales  $\Leftrightarrow$  two time units: chose the slower one!!

$$\vec{N}(t+1) = S \circ \overbrace{F \circ F \cdots \circ F}^{\text{k times}} (\vec{N}(t)) = S \circ F^{(k)} (\vec{N}(t))$$

In our case it reads as

$$\vec{N}(t+1) = \mathcal{S}(\mathcal{F}^k \vec{N}(t)) \cdot \mathcal{F}^k \vec{N}(t) \quad (1)$$

Being  $F_j$  stochastic implies

$$\lim_{k \rightarrow \infty} \mathcal{F}_j^k = \mathbf{v}_j \mathbf{1}_j^T$$

where  $\mathbf{v}_j$  and  $\mathbf{1}_j^T$  are its left and right main eigenvectors.

$$\lim_{k \rightarrow \infty} \mathcal{F}^k = \bar{\mathcal{F}} = \underbrace{\text{diag}(\mathbf{v}_1 \cdots \mathbf{v}_c)}_{A^c \times c} \cdot \underbrace{\text{diag}(\mathbf{1}_1^T \cdots \mathbf{1}_c^T)}_{c \times A^c} = \mathcal{E} \cdot \mathcal{G}$$

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# Approximate aggregation

We approximate the complete system

$$\vec{N}(t+1) = \mathcal{S}(\mathcal{F}^k \vec{N}(t)) \cdot \mathcal{F}^k \vec{N}(t)$$

of dimension  $A \cdot c$  by the auxiliary system

$$\vec{N}(t+1) = \mathcal{S}(\bar{\mathcal{F}} \vec{N}(t)) \cdot \bar{\mathcal{F}} \vec{N}(t) = \mathcal{S}(\mathcal{E} \cdot \mathcal{G} \vec{N}(t)) \cdot \mathcal{E} \cdot \mathcal{G} \vec{N}(t) \quad (2)$$

Defining the global variables

$$\vec{Y} = \mathcal{G} \vec{N} \quad y_j = n_{j1} + \dots + n_{jA}$$

yields the aggregated system, of dimension  $c$ ,

$$\vec{Y}(t+1) = \mathcal{G} \cdot \mathcal{S}(\mathcal{E} \vec{Y}(t)) \cdot \mathcal{E} \vec{Y}(t) \quad (3)$$

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## General results

If  $\vec{Y}^* \in \mathbb{R}^A$  is a hyperbolic fixed point of the reduced system (3) then

- 1  $\forall k \geq k_0$  the complete system (1) has an unique fixed point  $\vec{X}_k^* \in \bar{B}_r(\mathcal{E} \vec{Y}^*)$  which is hyperbolic and

$$\lim_{k \rightarrow \infty} \vec{X}_k^* = \mathcal{E} \vec{Y}^*$$

- 2  $\vec{Y}^*$  is A.S. (U.) if, and only if  $\vec{X}_k^*$  ( $\forall k \geq k_1$ ) are A.S. (U.)
- 3 The basin of attraction of  $\vec{X}_k^*$  can be described from that of  $\vec{Y}^*$

- L. Sanz, R. Bravo de la Parra, E. Sánchez. *Two time scales non-linear discrete models approximate reduction*. Journal of Difference Equations and Applications, 14 (2008), No. 6, 607–627.

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# Two patches competing species with fast movements

**Notations:**  $\vec{N} = (N_1^1, N_1^2, N_2^1, N_2^2) = (\vec{N}_1, \vec{N}_2)$ ,  $n_i = N_i^1 + N_i^2$

**Fast dynamics:** constant displacement  $0 < p_i, q_i < 1$

$$\mathcal{F}_i = \begin{pmatrix} 1 - p_i & q_i \\ p_i & 1 - q_i \end{pmatrix}, \quad \lim_{k \rightarrow \infty} \mathcal{F}_i^k = \begin{pmatrix} \nu_i^* & \\ & 1 - \nu_i^* \end{pmatrix} \begin{pmatrix} 1 & \\ & 1 \end{pmatrix} = \bar{\mathcal{F}}_i$$

**Slow dynamics:** local Leslie-Gower competition model  $b_i^j, c_{ij}^k > 0$

$$\left\{ \begin{array}{l} N_1^1(t+1) = \frac{b_1^1}{1 + c_{11}^1 N_1^1(t) + c_{12}^1 N_2^1(t)} N_1^1(t) \\ N_1^2(t+1) = \frac{b_1^2}{1 + c_{11}^2 N_1^2(t) + c_{12}^2 N_2^2(t)} N_1^2(t) \\ N_2^1(t+1) = \frac{b_2^1}{1 + c_{21}^1 N_1^1(t) + c_{22}^1 N_2^1(t)} N_2^1(t) \\ N_2^2(t+1) = \frac{b_2^2}{1 + c_{21}^2 N_1^2(t) + c_{22}^2 N_2^2(t)} N_2^2(t) \end{array} \right. \Rightarrow S(\vec{N}) = S(\vec{N}) \vec{N}$$

- J.M. Cushing, S. Levarge, N. Chitnis, S.M. Henson. Some Discrete Competition Models and the Competitive Exclusion Principle *Journal of Difference Equations and Applications*, **10**(13-15):1139-1151, 2004.

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# Aggregated model and global variables

Complete model: 
$$\vec{N}(t+1) = \mathcal{S} \left( \mathcal{F}^k \vec{N}(t) \right) \cdot \mathcal{F}^k \vec{N}(t)$$

Aggregated system: 
$$\begin{cases} n_1(t+1) = f(n_1(t), n_2(t))n_1(t) \\ n_2(t+1) = g(n_1(t), n_2(t))n_2(t) \end{cases} \quad \text{where}$$

$$f(n_1, n_2) = \left( \frac{b_1^1 \nu_1^*}{1 + c_{11}^1 \nu_1^* n_1 + c_{12}^1 \nu_2^* n_2} + \frac{b_1^2 (1 - \nu_1^*)}{1 + c_{11}^2 (1 - \nu_1^*) n_1 + c_{12}^2 (1 - \nu_2^*) n_2} \right)$$

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**All solutions in  $[0, \infty) \times [0, \infty)$  converge to an equilibrium in an eventually monotonic manner.**

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## Results from the aggregated system:

- The trivial equilibrium point  $(0, 0)$ .
- The semitrivial equilibrium points  $(n_1^*, 0)$ ,  $(0, n_2^*)$  always exist and can be explicitly calculated.
- No explicit expression for positive equilibrium (if any)

Equilibrium	Asint stable	Unstable
$(0, 0)$	$0 < b_{ij}^r < 1$	$b_{ij}^r > 1$
$(n_1^*, 0)$	$g(n_1^*, 0) < 1$	$g(n_1^*, 0) > 1$
$(0, n_2^*)$	$f(0, n_2^*) < 1$	$f(0, n_2^*) > 1$
		global coex

**Are there displacements-competition tradeoffs?** Assume:

- \* Spatial homogeneity
- \* Asymmetric competition

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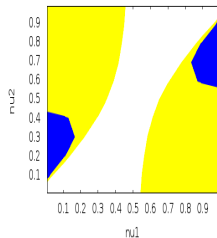
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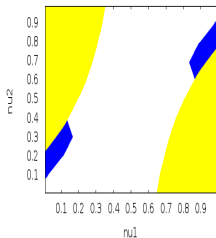
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# Numerical experiments

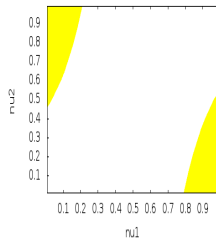
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$$b = 1.5, c_{21} = 3, c_{12} = 0.9$$



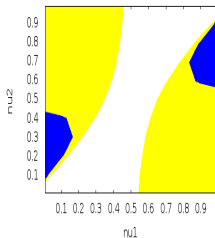
White  
Yellow  
Blue

species 1 globally excludes species 2  
global coexistence  
species 2 globally excludes species 1

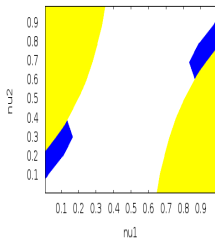
- D. Nguyen Ngoc, R. Bravo de la Parra, M.A. Zavala, P. Auger Competition and species coexistence in a metapopulation model: Can fast asymmetric migration reverse the outcome of competition in a homogeneous environment? *Journal of Theoretical Biology*, 266:256-263, 2010.

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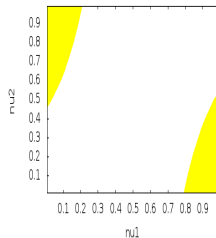
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# Thanks; questions?

## About approximate aggregation of discrete systems

- R. Bravo de la Parra, M. Marva, E. Sanchez, L. Sanz  
Reduction of Discrete Dynamical Systems with Applications to Dynamics Population Models  
Mathematical Models of Natural Phenomena, (to appear).
- L. Sanz, R. Bravo de la Parra, E. Sanchez. *Two time scales non-linear discrete models approximate reduction*.  
Journal of Difference Equations and Applications, 14 (2008), No. 6, 607–627.

## About approximate aggregation, including ODEs and PDEs

- P. Auger, R. Bravo de la Parra, J.-C. Poggiale, E. Sanchez, T. and Nguyen-Huu  
Aggregation of variables and applications to population dynamics  
In P. Magal, S. Ruan (Eds.), *Structured Population Models in Biology and Epidemiology*,  
Lecture Notes in Mathematics 1936, Mathematical Biosciences Subseries, Springer Verlag, Berlin, 2008, 209–263.