# The Leslie-Gower competition model with fast dispersal

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#### • Dispersal-competition tradeoff?

- Does fast dispersal yield new dynamic scenarios? The Leslie-Gower competition model (discrete) allows
  - Species coexistence.
  - One species extinction (unconditionally).
  - One species extinction (depending on initial values).



## Notation S: competition, demography F: dispersal $S(x,y) = \begin{pmatrix} \frac{b_1}{1 + c_{11}x + c_{12}y}x \\ \frac{b_1}{1 + c_{21}x + c_{22}y}y \end{pmatrix}$





#### Notation

- S: competition, demography
- $F\colon$  dispersal

$$S(x,y) = \begin{pmatrix} \frac{b_1}{1 + c_{11}x + c_{12}y} x \\ \frac{b_1}{1 + c_{21}x + c_{22}y} y \end{pmatrix}$$





 $\begin{array}{l} \text{Notation} \\ S: \text{ competition, demography} \\ F: \text{ dispersal} \end{array} \qquad \qquad S(x,y) = \left( \begin{array}{c} \frac{b_1}{1 + c_{11}x + c_{12}y} \\ \frac{b_1}{1 + c_{21}x + c_{22}y} \\ y \end{array} \right)$ 

We choose the slow time unit t  $t = \frac{k \text{ times}}{1 + 1}$  $N(t+1) = S \circ \overrightarrow{F \circ F} \circ \cdots \overrightarrow{F} (N(t)) = S \circ F^{(k)} (N(t))$ 

Notation: 
$$N = (N_1^{1}, N_1^{2}, N_2^{1}, N_2^{1}, N_2^{2}), \qquad n_i = N_i^{1} + N_i^{2}$$

**Fast dynamics:** constant dispersal rates  $0 < p_i, q_i < 1$ 

$$F(N) = \begin{pmatrix} \mathcal{F}_1 & 0 \\ 0 & \mathcal{F}_2 \end{pmatrix} N, \quad \text{where} \quad \mathcal{F}_i = \begin{pmatrix} 1 - p_i & q_i \\ p_i & 1 - q_i \end{pmatrix}$$

**Slow dynamics:** local Leslie-Gower competition model  $b_i^j, c_{ij}^k > 0$ 

$$S(N) = \left(\frac{b_1^1 N_1^1}{1 + c_{11}^1 N_1^1 + c_{12}^1 N_2^1}, \frac{b_1^2 N_1^2}{1 + c_{11}^2 N_1^2 + c_{12}^2 N_2^2}, \frac{b_2^1 N_2^1}{1 + c_{21}^2 N_1^1 + c_{22}^1 N_1^1 + c_{22}^1 N_2^1}, \frac{b_2^2 N_2^2}{1 + c_{21}^2 N_1^2 + c_{22}^2 N_2^2}\right)$$

$$N(t+1) = S \circ F^{(k)}(N(t))$$

Given that 
$$\lim_{k \to \infty} \mathcal{F}_i^k N_i = \begin{pmatrix} \nu_i^* \\ 1 - \nu_i^* \end{pmatrix} n_i$$
 where  $\nu_i^* = \frac{q_i}{p_i + q_i}$  yields the so-called *auxiliary system*

$$N(t+1) = S \circ \bar{F}(N(t))$$

A center manifold result yields the aggregated system:

$$\begin{cases} n_1(t+1) = f(n_1(t), n_2(t))n_1(t) \\ n_2(t+1) = g(n_1(t), n_2(t))n_2(t) \end{cases}$$

where

$$\begin{split} f(n_1, n_2) &= \left(\frac{b_1^1 \nu_1^*}{1 + c_{11}^1 \nu_1^* n_1 + c_{12}^1 \nu_2^* n_2} + \frac{b_1^2 (1 - \nu_1^*)}{1 + c_{11}^2 (1 - \nu_1^*) n_1 + c_{12}^2 (1 - \nu_2^*) n_2}\right) \\ g(n_1, n_2) &= \left(\frac{b_2^1 \nu_2^*}{1 + c_{11}^1 \nu_1^* n_1 + c_{22}^1 \nu_2^* n_2} + \frac{b_2^2 (1 - \nu_2^*)}{1 + c_{21}^2 (1 - \nu_1^*) n_1 + c_{22}^2 (1 - \nu_2^*) n_2}\right) \end{split}$$

## Approximate aggregation $N(t+1) = S \circ F^{(k)}(N(t))$

#### General results

Let  $n^* = (n_1^*, n_2^*) \in \mathbb{R}^2$  be a hyperbolic fixed point of the reduced system. Then

• For all  $k \ge k_0$  the slow-fast system has an unique fixed point  $N_k^*$  which is hyperbolic and

$$\lim_{k \to \infty} N_k^* = (\nu_1^* n_1^*, (1 - \nu_1^*) n_1^*, \nu_2^* n_2^*, (1 - \nu_2^*) n_2^*)$$

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$$n^*$$
 is A.S. (U.)  $\Leftrightarrow N_k^*$  is A.S. (U.) for all  $k \ge k_1$ .

Solution of  $N_k^*$  can be described from that of  $n^*$ .

<sup>\*</sup> L. Sanz, R. Bravo de la Parra, E. Sánchez (2008). Two time scales non-linear discrete models approximate reduction. Journal of Difference Equations and Applications, 14, No. 6, 607–627.

#### Results from the aggregated system:

All solutions in  $[0,\infty)\times[0,\infty)$  converge to an equilibrium in an eventually monotonic manner

- Explicit expressions for fixed points  $(n_1^*, 0), (0, n_2^*)$ .
- Explicit conditions for the stability of  $(n_1^*, 0), (0, n_2^*)$ .
- Complicated expression for coexistence equilibrium.
- Spatial homogeneity: outcomes as in the Leslie-Gower model, but **dispersal does matter**!!
- Spatial heterogeneity: up to 3 coexistence equilibrium points!

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### Dispersal-competition tradeoff?

- Spatial homogeneity  $c_{12}^1 = c_{12}^2$ ,  $c_{21}^1 = c_{21}^2$ ,  $c_{ii}^1 = c_{ii}^2$ ,  $b_1^1 = b_1^2 = b_2^1 = b_2^2$ .
- In absence of dispersal: species 1 outcompetes species 2.



 $b = 1.5, c_{21} = 1.1, c_{12} = 0.9$ 

Bluespecies 2 extinctionWhiteglobal coexistenceGreenspecies 1 extinction

## Dispersal-competition tradeoff? spatial homogeneity

• In absence of dispersal: species 1 outcompetes species 2.

$$b = 1.5, c_{21} = 1.1, c_{12} = 0.9$$

  $b = 1.5, c_{21} = 1.5, c_{12} = 0.85$ 







Redconditional extinctionWhiteglobal coexistenceGreenspecies 1 extinctionBluespecies 2 extinction

## Dispersal-competition tradeoff? spatial homogeneity

#### • In absence of dispersal: conditional extinction.

 $b = 1.5, c_{21} = 1.1, c_{12} = 1.1$ 



 $b = 1.5, c_{21} = 1.5, c_{12} = 1.3$ 



 $b = 1.5, c_{21} = 3, c_{12} = 1.7$ 



Red
White
Green
Blue

conditional extinction
global coexistence
species 1 extinction
species 2 extinction

## Dispersal-competition tradeoff? spatial homogeneity

• In absence of dispersal: coexistence.

 $b = 1.5, c_{21} = 0.9, c_{12} = 0.9$ 



 $b = 1.5, c_{21} = 0.9, c_{12} = 0.7$ 







Redconditional extinctionWhiteglobal coexistenceGreenspecies 1 extinctionBluespecies 2 extinction

## Spatial heterogeneity allows new dynamics

\* At most three coexistence equilibria.



• There exists a trade-off between competition and (fast) dispersal.

 Fast dispersal between heterogeneous regions may lead to new dynamical scenarios.

## Thank you; questions?